



P.N. Lebedev Physical Institute  
Russian Academy of Sciences



# Free-Standing Cryogenic Target Facility created at the Lebedev Physical Institute

Elena Koresheva

2<sup>nd</sup> ETFW, Abingdon, October 27, 2008

# Free-standing target (FST) approach to cryogenic target technology and delivery is under development in the Cryotarget Group of Lebedev Physical Institute (LPI) over the last 20 years

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## □ FST APPROACH

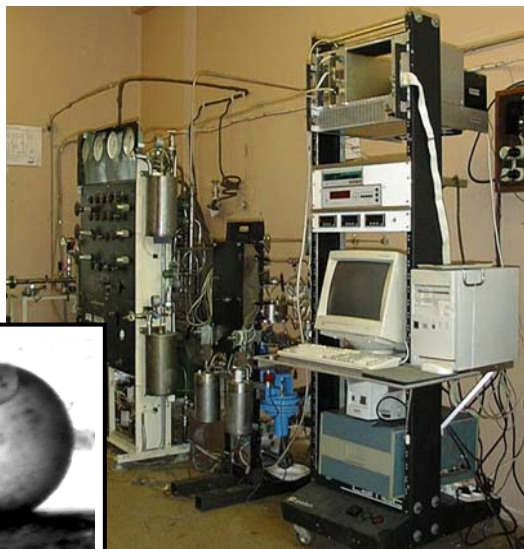
Operation with free-standing targets at each production step:  
fuel filling → fuel layering → target injection

## □ MOTIVATION

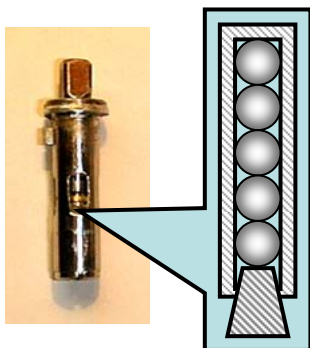
- time and space minimization at each production step ⇒  
⇒ tritium inventory minimization
- possibility for high rep-rate target fabrication and injection

# THE FST-SYSTEM CREATED AT LPI ALLOWS THE REP-RATE FABRICATION OF A FUEL LAYER INSIDE MOVING FREE-STANDING SHELLS

- shell diameter of 0.8÷1.8 mm
- layering time 4÷15 sec
- cryogenic layer thickness of 10÷100  $\mu\text{m}$
- production rate up to 0.1 Hz (currently)



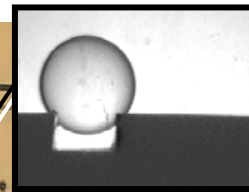
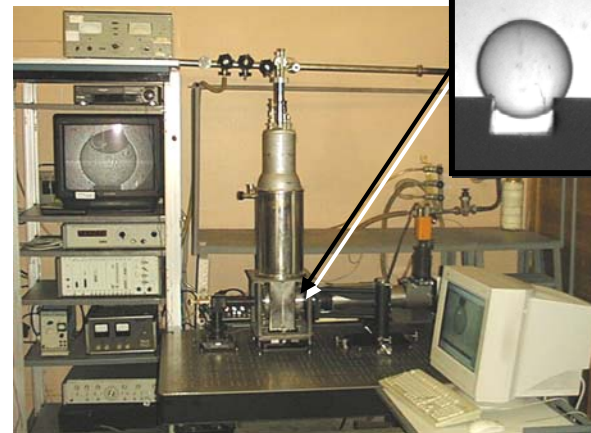
Computer-aided facility for micro shells permeation filling with gas up to 1000 atm at 300 K



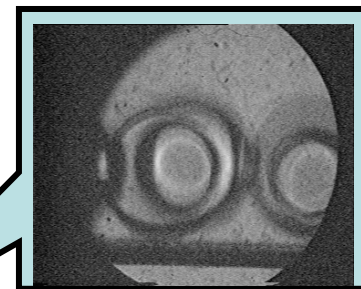
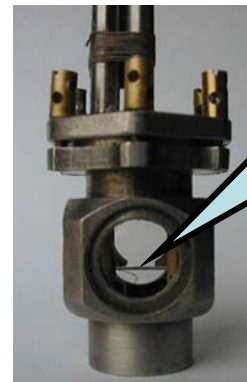
Shell container for transporting a batch of fuel filled shells at 300 K



FST LAYERING MODULE



A 100-projections visual-light tomograph for precise control of the free-standing microshells and cryogenic targets



Rotating & bouncing cell (R&B cell) for new FST experiments



## COMPUTER AIDED FILL FACILITY

Fill pressure: 10-to-1000 atm

Fill procedure:

- ramp filling ( $\Delta P = \text{const}$ )
- step filling ( $P = \text{const}$ )

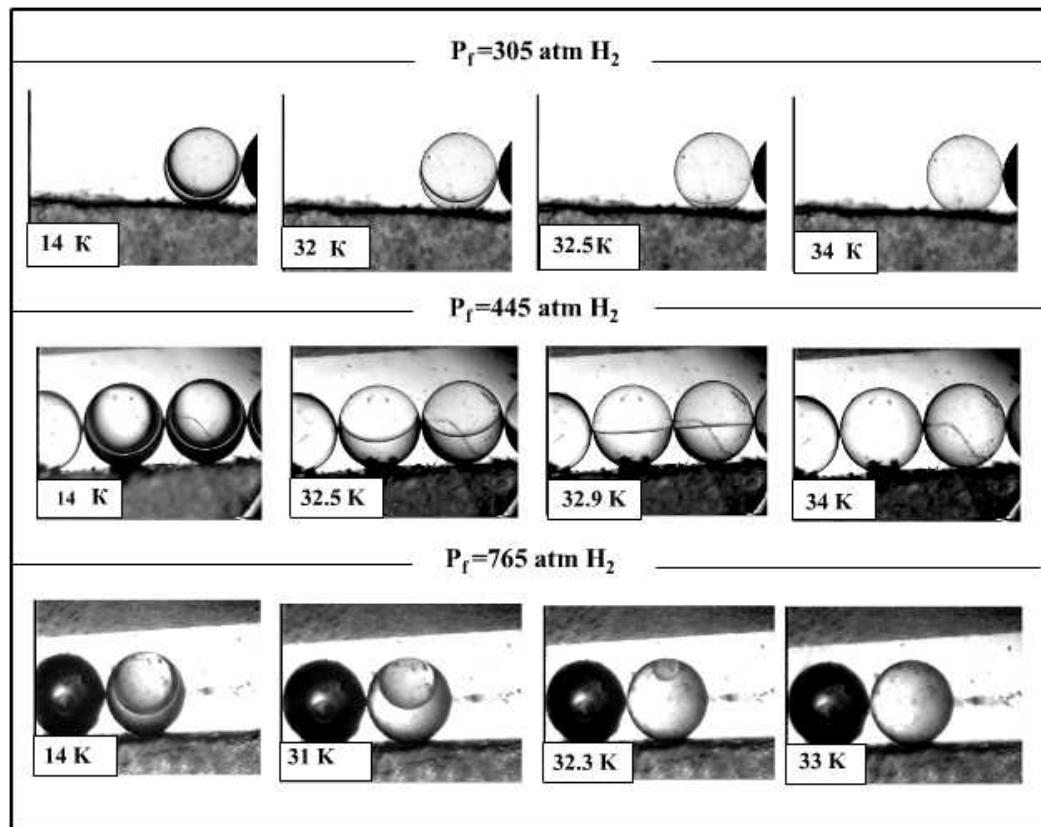
Work temperature:

- 300 K (CH shells) & 650 K (glass shells)

Work gases:

- D<sub>2</sub>, H<sub>2</sub>, H<sub>2</sub>+D<sub>2</sub> (different mixtures) & Ar, Ne, Xe, He (as additives)

## Permeation fuel filling of a batch of free-standing shells

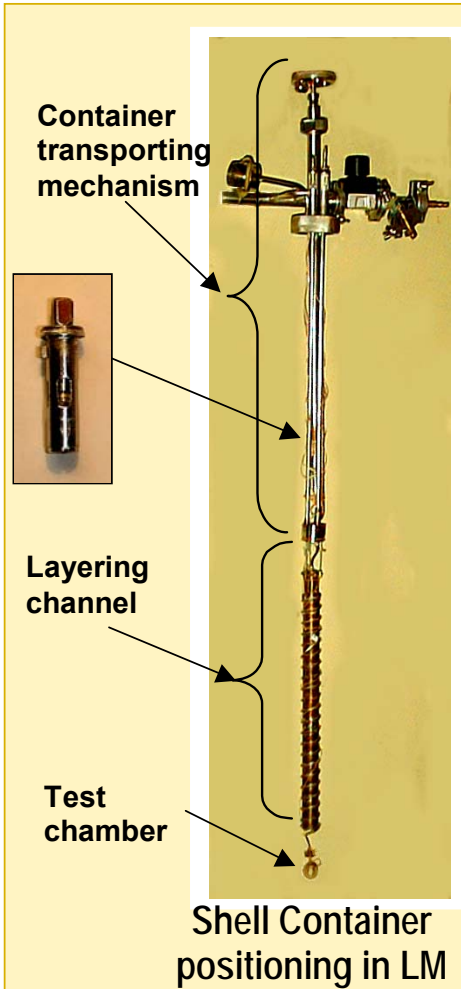


## FILLING CAPABILITY OF THE FACILITY





# Experimental facility for research in the area of cryogenic layering inside free-standing targets

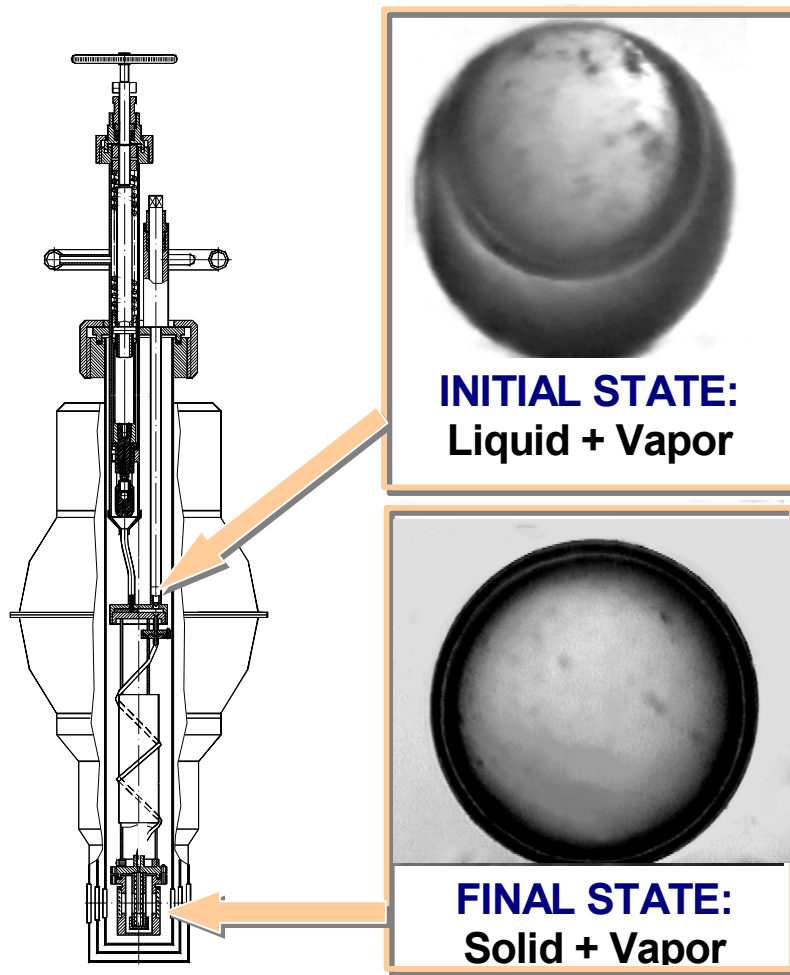


Layering module in assembly with commercial cryostat UTREX-1-RTA



Experimental Facility

The layering module operates according the FST method:  
rapid fabrication of a fuel layer inside moving free-standing target



**CH SHELL  $\varnothing$  1.0-1.8 mm**

**$P_f = 10\div 1000$  atm  
at 300 K**

**LAYERING TIME**

**$t \leq 15$  sec**

**$W = 10\text{-to-}100$   $\mu\text{m}$**

# The layering channels of different shape for the FST technology optimization

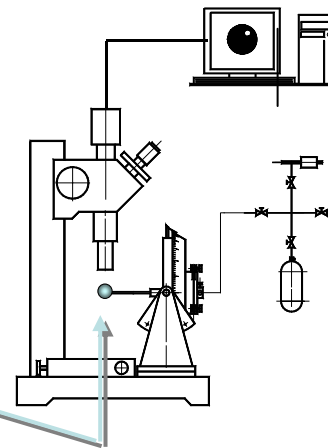
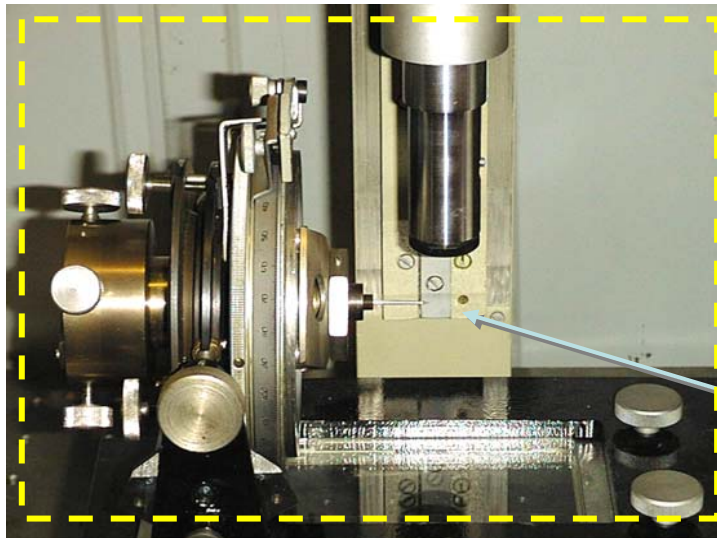


# Tomograph "Shell Tester" to control CH and glass shells parameters

## ❑ Scanning Parameters

- Full scanning angle: 360 deg.
- Number of projections (max) – 1000
- Positioning accuracy:  $\pm 1.5$  min

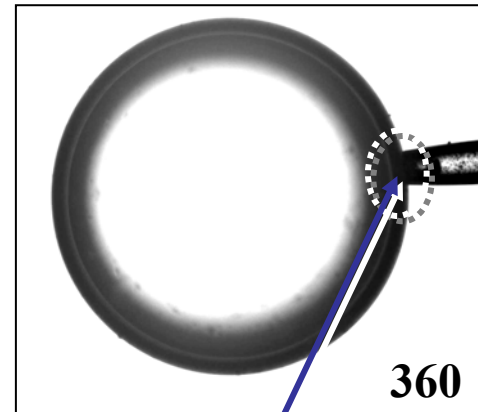
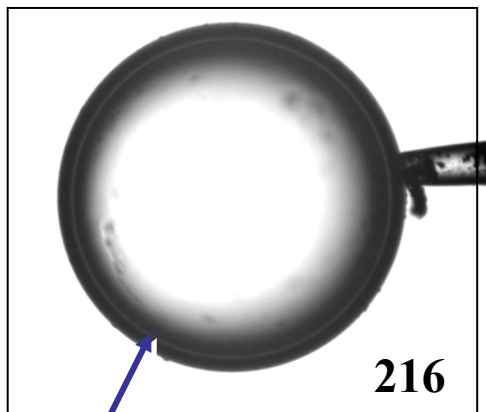
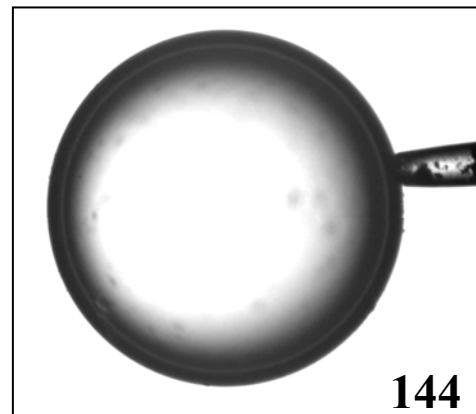
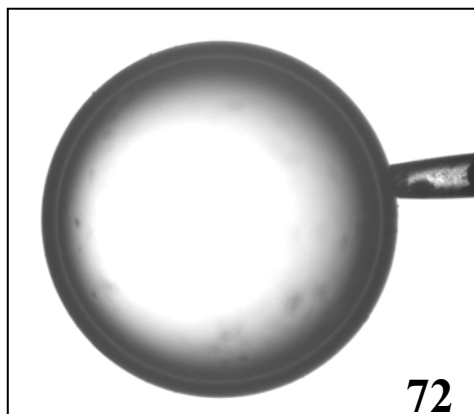
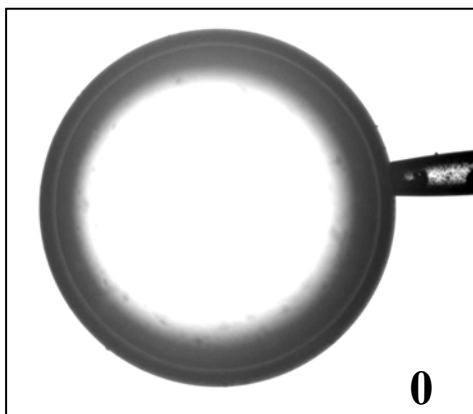
## ❑ Spatial resolution: 1 $\mu\text{m}$



Shell vacuum mount



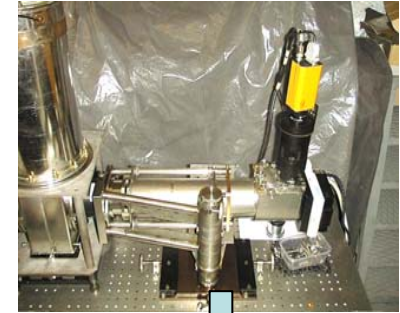
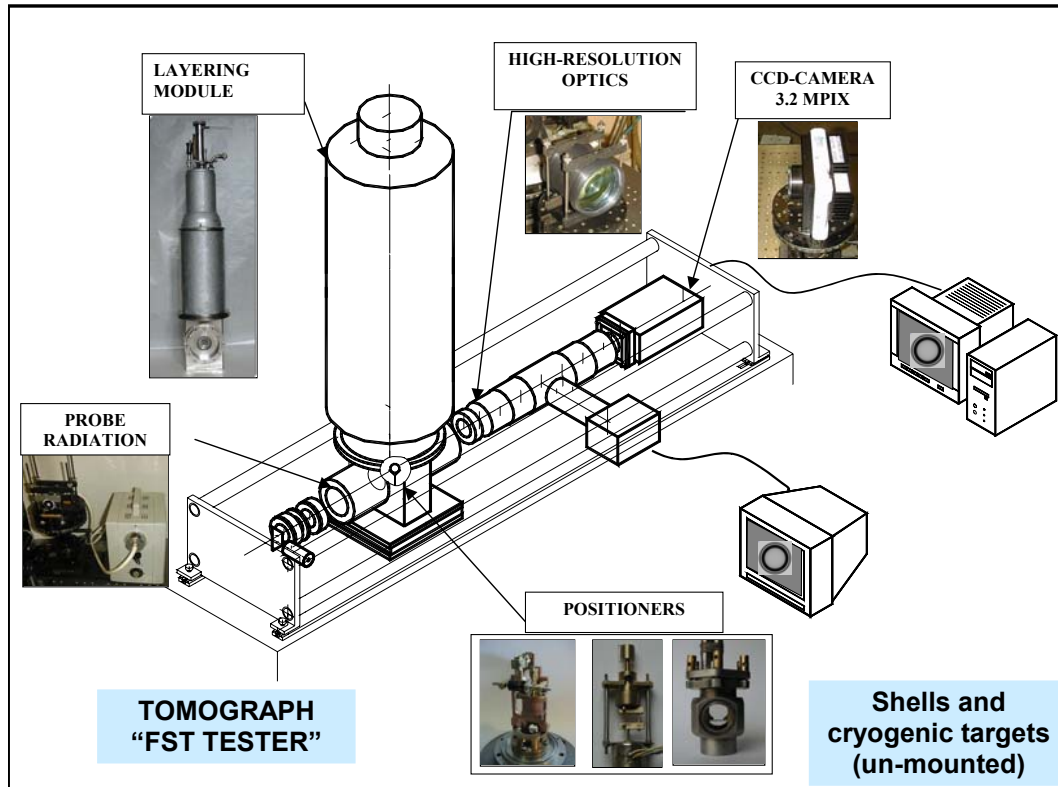
# Tomograph Shell Tester: image projections data



Bright band

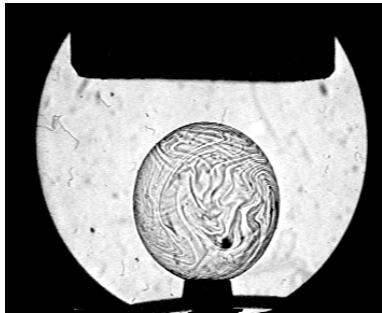
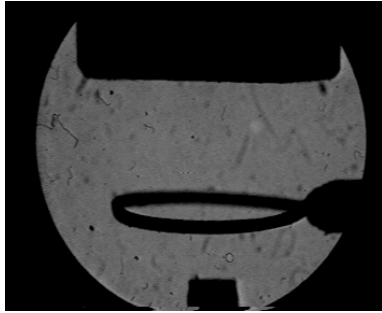
"vacuum"  
mount

# A 100-projections visual-light micro-tomograph for free-standing microshells and cryogenic targets precise characterization



- |  |                        |  |          |
|--|------------------------|--|----------|
| <input type="checkbox"/> Target temperature:           | room & cryo (77–4.2 K) | <input type="checkbox"/> Current number of projections:        | 100      |
| <input type="checkbox"/> Probing radiation wavelength: | 490±7 nm               | <input type="checkbox"/> Spatial resolution in one projection: | ~1 μm    |
| <input type="checkbox"/> Total scanning angle:         | 360 degree             | <input type="checkbox"/> Studied target diameter:              | ≤ 1.5 mm |
| <input type="checkbox"/> Accuracy of positioning:      | ± (1.5–2.5) min        | <input type="checkbox"/> Accuracy of reconstruction:           | ~ 1 μm   |

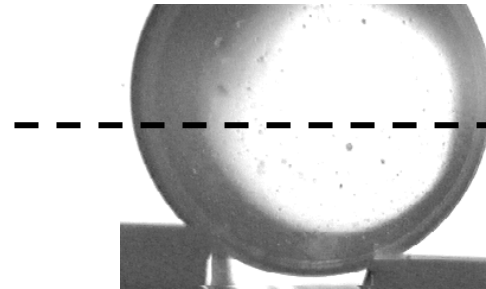
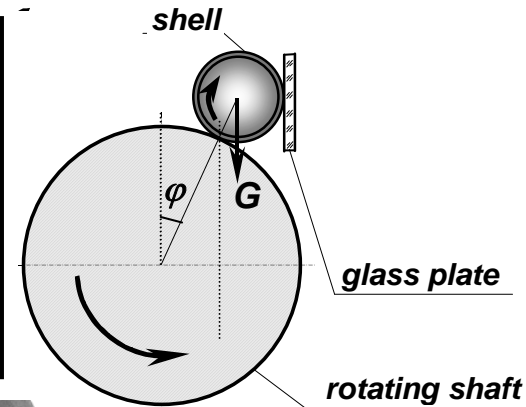
# DEVICES FOR FREE-STANDING TARGET POSITIONING: TARGET ROTATING AROUND THE FIXED AXIS



UP-1: Rotating around vertical axis

## PERFORMANCE DATA

Scanning angle 2.5 deg., full angle 360 deg.  
Target  $\varnothing$  – unlimited  
Control of projection angle: stepper motor  
Number of rotation axes – 1  
Number of projections – 144 (max)

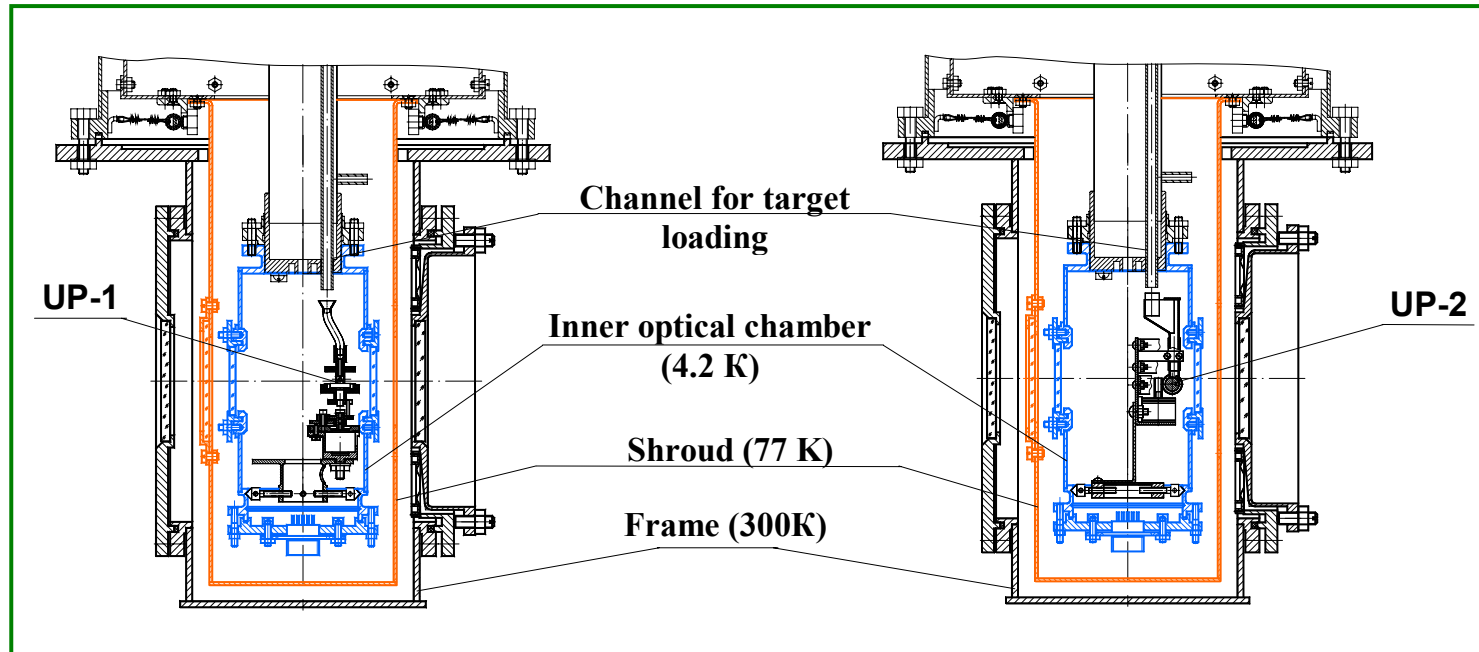
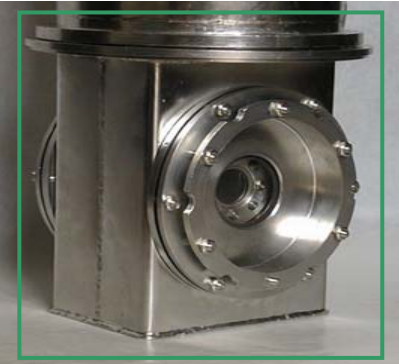


UP-2:  
Rotating around  
horizontal axis

## PERFORMANCE DATA

Scanning angle 2.9 deg., full angle 360 deg.  
Target  $\varnothing$  –  $\geq 1.2$  mm  
Control of projection angle: stepper motor  
Number of rotation axes – 1  
Number of projections – 124 (max)

# Positioning devices disposal inside the tomographic test chamber of cryostat



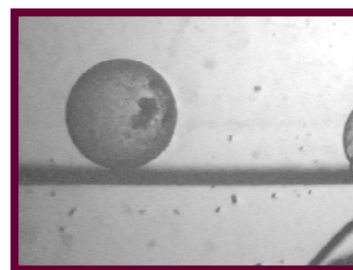
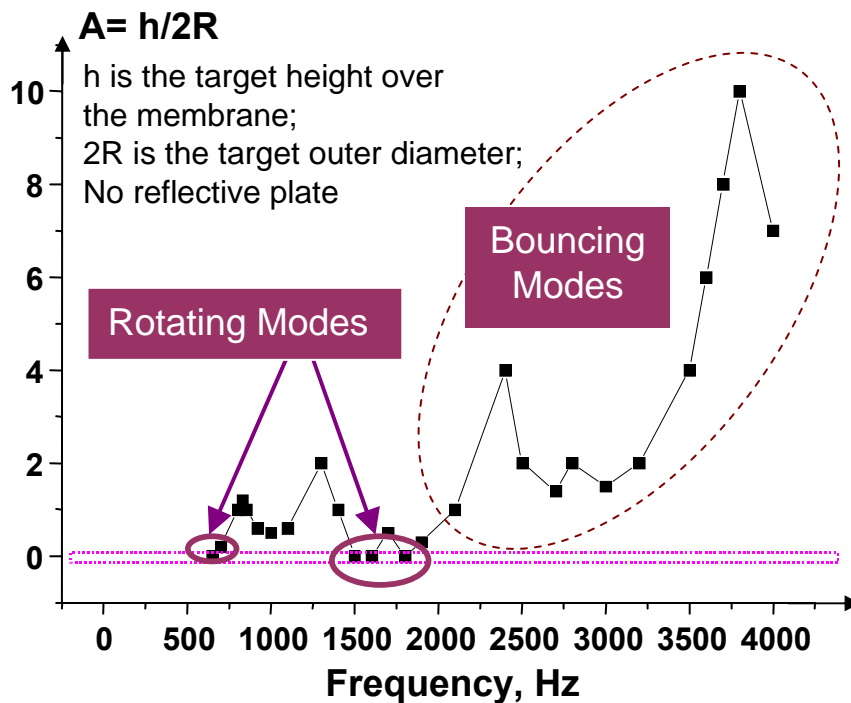
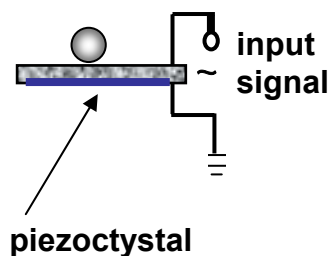
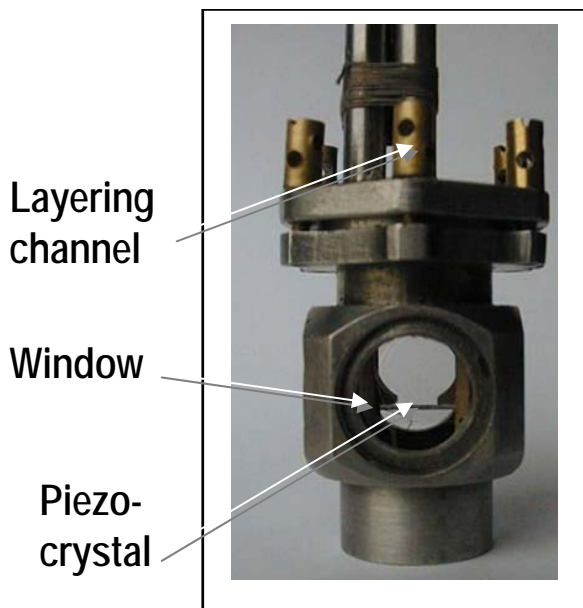
## PERFORMANCE DATA

- Observation aperture (max):  $63^\circ$
- Outer window diameter: 54 mm
- Target/objective stand-off distance (min): 54 mm
- Work temperatures range: 4.2-20 K, 300 K

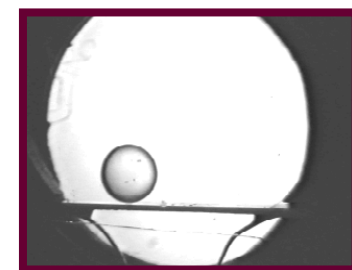


# ANOTHER APPROACH TO STUDY THE TARGET ALL OVER AROUND: target positioning with random angle of displacement using the R&B cell

- Control of the target movement is based on the reverse piezo-electrical effect.
- The couple "membrane & target" is driven by an input signal of 0.3 Hz -to- 4.0 MHz
- Device has been tested at the temperature of 4.2 -to-77 K and 300 K

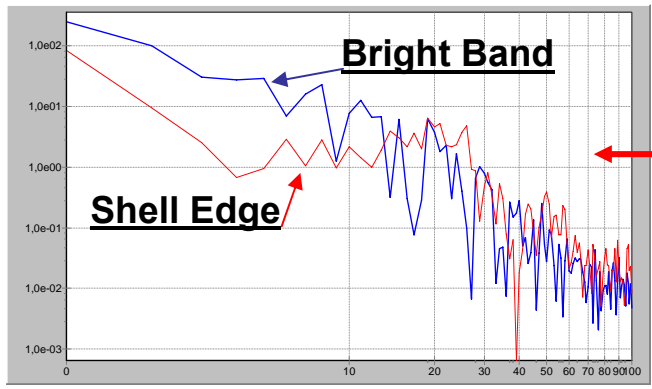
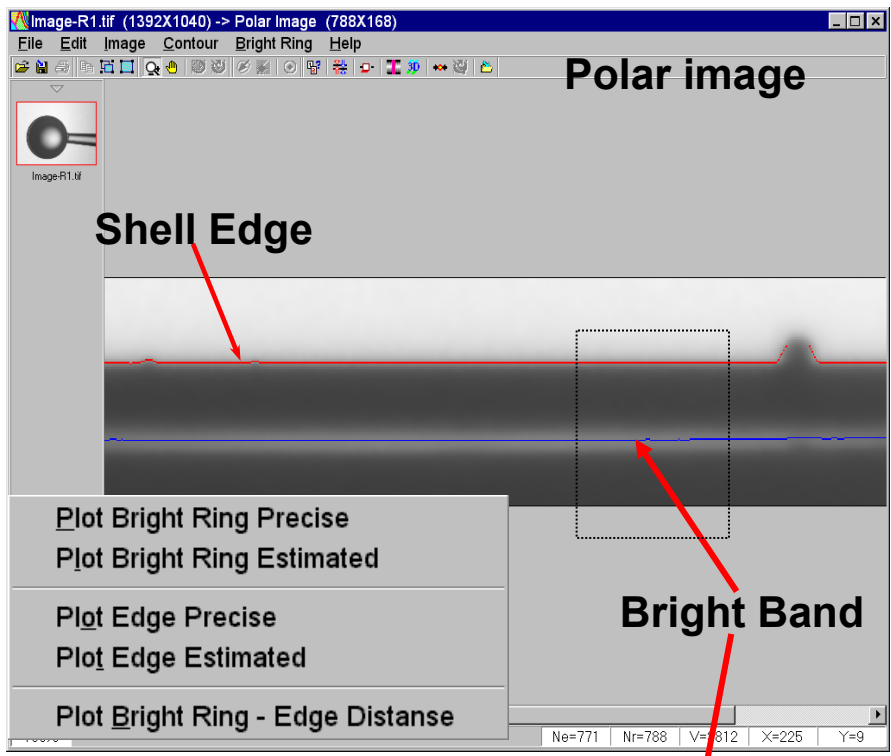
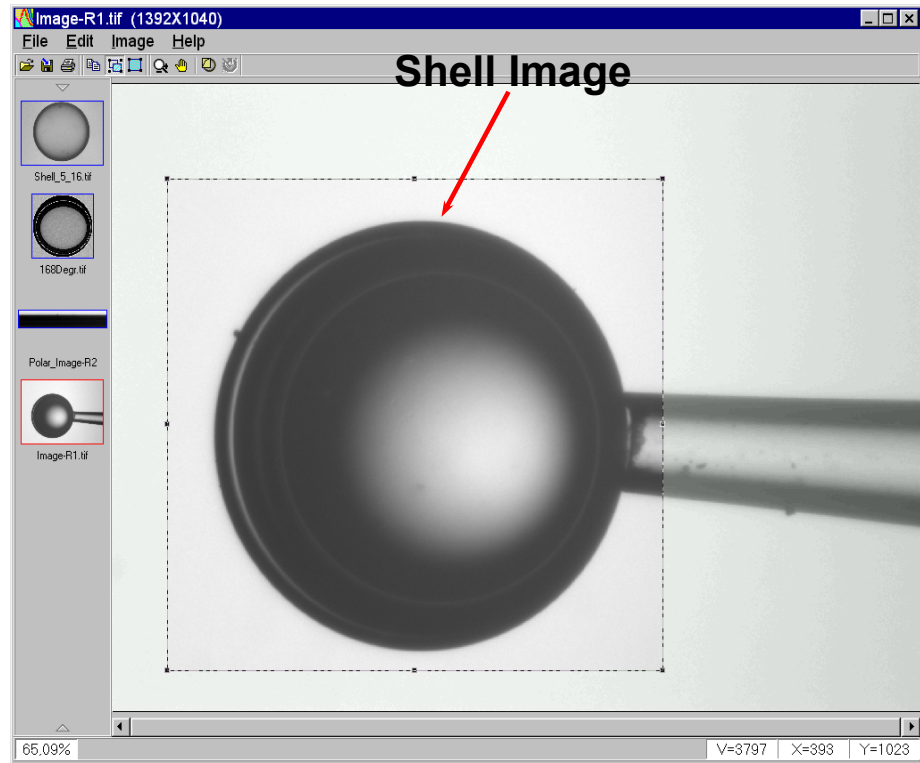


Target rotation all over around at 6 K, 1.7 MHz



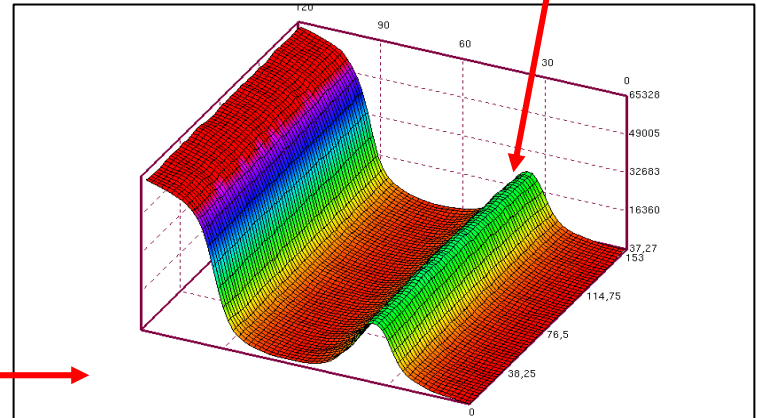
Target bouncing, T=77 K, 3.7 MHz

# Target Studio software for 3D reconstruction of target parameters using a set of its backlit images. Reconstruction algorithm is based on the analysis of bright band position on target backlit images.



Power spectrum

3-D visualization



# 3D reconstruction of the parameters

## of the free-standing CH shell using its 90 backlit projections.

Reconstruction is performed by means of specially developed software *Target Studio*.

### Reconstructed Parameters

#### Shell's outer surface

Mean radius :: 712.4

Min radius :: 710.3

Max radius :: 716.7

Out of Round :: 0.4 %

#### Shell's inner surface

Mean radius :: 690.9

Min radius :: 687.3

Max radius :: 694.1

Out of Round :: 0.5 %

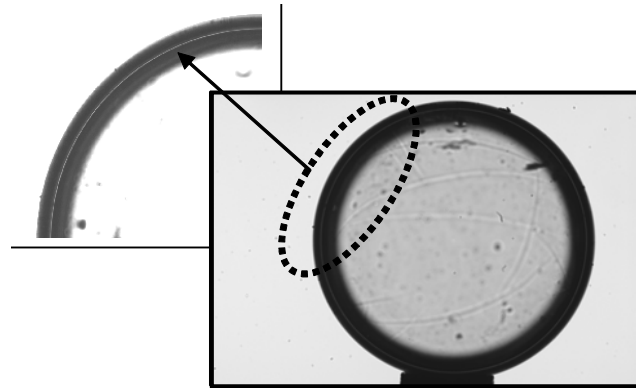
#### Wall parameters

Mean wall :: 21.5

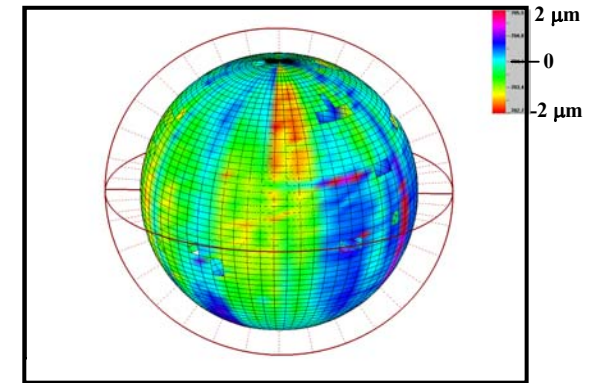
Min wall :: 17.7

Max wall :: 25.6

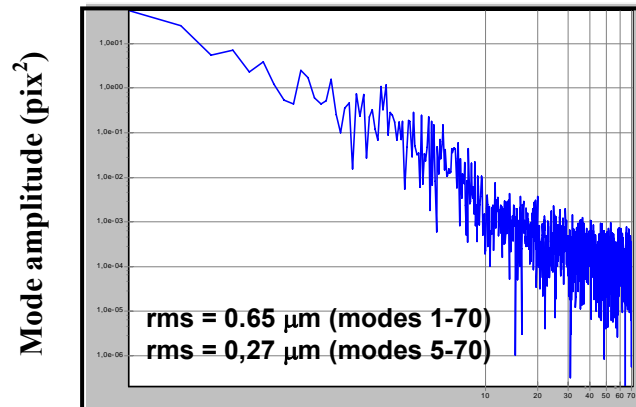
Non-uniformity :: 19.0 %



Shadow projection of polystyrene microshell (UP-1 positioner)

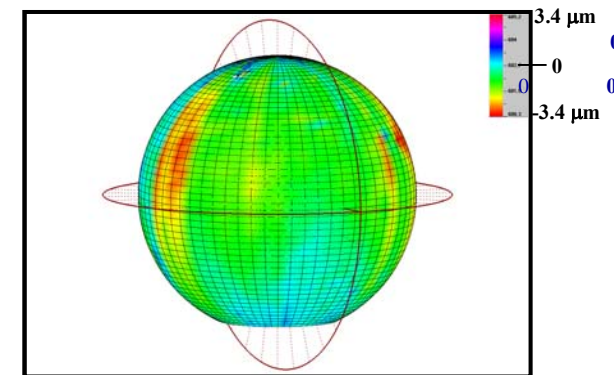


Outer surface of microshell (reconstruction)



Mode number

Fourier spectrum of bright band



Inner surface of microshell (reconstruction)

# MICROSHELLS THAT WE USED IN THE CRYOGENIC EXPERIMENTS over the period of 1987-2007

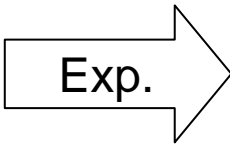
- **Products of LPI, Russia (1987-2007)**

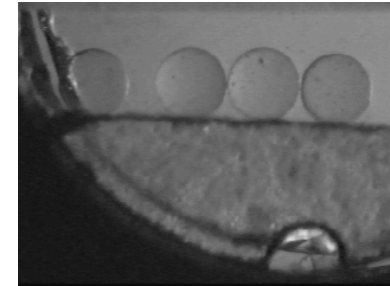
Method: drop tower

- **Glass shells**  $\varnothing 0.3 \div 0.6$  mm,  $\Delta R = 3-15$   $\mu\text{m}$ ,  $\sigma \leq 350$  kg/mm<sup>2</sup> (at 300 K)

Methods: drop tower and ballistic furnace

- **CH shells**  $\varnothing 0.7 \div 1.5$  mm,  $\Delta R = 8-20$   $\mu\text{m}$

|   |                               |            |             |            |
|---|-------------------------------|------------|-------------|------------|
| Exp.  | <b>T, K</b>                   | <b>300</b> | <b>200</b>  | <b>100</b> |
|   | $\sigma$ , kg/cm <sup>2</sup> | <b>200</b> | <b>440</b>  | <b>680</b> |
| <b>330</b>  |                               | <b>720</b> | <b>1100</b> |            |



Target heating from 40 K to the moment of CH shell blowing up under the inner pressure action

- **Products of ILE, Japan (2002-2004)**

Method: microencapsulating

- **CH shells**  $\varnothing 1.4 \div 1.8$  mm,  $\Delta R = 18-72$   $\mu\text{m}$ ,  $\sigma < 100$  kg/cm<sup>2</sup> (at 300 K)